**Trouble shooting**

**In the 2nd assignment we did I learned a lot about trouble shooting you may wondering what is trouble shooting? I'll give you a definition in my own words.**

**Trouble shoot: When something goes wrong but you think of ways on how to fix it.**

**So this is what happened to me I was doing my program with a red peice of paper. When it was time to line fowollow it started spinning for no reason, but thats what I thought. Then I thought maybe the color sensor was not seeing red. So I got a darker shade of red and started programing. What I programed the robot to do was to show eyes when it saw something other than red and show theeth when it saw red. For the paper it showed a pair of eyes then for the darker shade of red it showed theeth. I could not finish the program because that happened saturday night.**

**What else to do**

**If your robot starts doing some random thing here is what you can do.**

**.Look at your program and look at the stuff in it to make it easier to read coment the blocks**

**.If your program is good or fixed take look at the port view and see if the large motor is being mistaked for a medeium motor it has happened.**

**.Take out all the wires and put them back in again**

**.If robot is spinning ike crazy see if you frogot to reset the gyro senser block or take out the wire than put it back again**

**.If you feel the color sensor is not sensing the color do what I did. Don't just do something with out testing your theory.**